# Numerical Approach to Dissipative Weak Solutions to the Euler Equations

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#### Scaling in 'real' turbulent flow

(i) Kolmogorov scaling law (K41)

$$E(k) \propto \epsilon^{2/3} k^{-5/3} \qquad 1/L \ll k \ll 1/\eta,$$
  
$$u(x+r,t) - u(x,t) \propto \epsilon^{1/3} r^{1/3} \qquad \eta \ll r \ll L$$

 $\epsilon \to (\text{const.})$  as  $\nu \to 0$ 

(ii) Energy dissipation rate  $\epsilon = \nu \sum_{k} |\mathbf{k}|^2 \langle |\hat{\mathbf{u}}(\mathbf{k},t)|^2 \rangle = \nu \frac{1}{V} \int \left\langle \left( \frac{\partial u_i}{\partial x_i} \right)^2 \right\rangle d\mathbf{x}$ 

conjecture

$$u(x+r,t) - u(x,t) \propto r^h$$
.

Exponent h is not limited to 1/3 (multifractal model)

dissipation, 1/3, multiple exponents h

#### Onsager's conjecture

- L. Onsager (1949)
  - 1. Turbulent dissipation could take place without viscosity.
  - 2. For this, the velocity field should not remain differentiable.
  - 3. "In fact, it is possible to show that the velocity field in such ideal turbulence cannot obey any LIPSCHITZ condition of the form

$$|\boldsymbol{u}(\boldsymbol{x}+\boldsymbol{r})-\boldsymbol{u}(\boldsymbol{x})|< ext{(const.)}\ r^h,$$

for any order h greater than 1/3; otherwise the energy is conserved."

•  $\nu = 0$ , the energy conserves for h > 1/3 and dissipates for  $h \le 1/3$ .

dissipation, 1/3, multiple exponents h

#### Onsager's conjecture: afterwards

- Precise formulation with the weak form of the Euler eqs. (Eyink 1994)
- The energy conservation for h > 1/3: proven by Eyink 1994; Constantin, E, Titi 1994.

$$|\boldsymbol{u}(\boldsymbol{x}+\boldsymbol{r})-\boldsymbol{u}(\boldsymbol{x})|< ext{(const.)} \ r^h$$

 The energy dissipation for h ≤ 1/3: proven recently by De Lellis and Székelyhidi 2013; Daneri and Székelyhidi 2016; Isett 2018; Buckmaster et al. 2019.

They constructed dynamic weak solutions with arbitrary (single) h in 0 < h < 1/3.

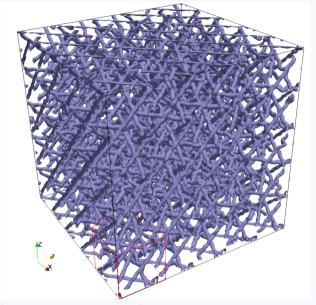
How? Can one do it numerically? (YES, BUT...)
Are the solutions relevant to real-world turbulence?

#### Why numerical simulation?

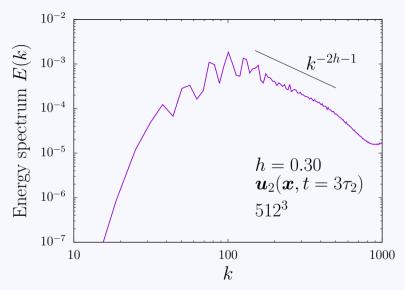
- How the dissipative weak solutions look like?
- Measure high-order structure functions, PDF, etc...
- Some aspects of the construction are similar to cascade models. It constructs velocity field  $|{\boldsymbol u}({\boldsymbol x}+{\boldsymbol r},t)-{\boldsymbol u}({\boldsymbol x},t)|\sim r^h~(0\leq h\leq 1/3)$  The cascade model approved by the (weak) Euler eqs.

#### Outline

- Dissipative weak solution of the Euler equations.
- Mathematical construction by De Lellis, Székelyhidi and co-workers
- Numerical simulation (on-going)
- Summary and outlook



Typical appearance as iso-surface of  $|\nabla \times \boldsymbol{u}_2(\boldsymbol{x},t)|$ Simulation of the construction of Buckmaster *et al.* (2019)



Energy spectrum of  ${\bf u}_2$  with h=0.30 Simulation of the construction of Buckmaster et al. (2019)

## Weak solution of the Euler eqs.

• Incompressible Euler eqs. with periodic boundary condition

$$\partial_t \boldsymbol{u} + (\boldsymbol{u} \cdot \nabla) \boldsymbol{u} = -\nabla p, \quad \nabla \cdot \boldsymbol{u} = 0$$

• test function  $\varphi(x,t)$  (smooth, finite support in x and t)

$$\overline{oldsymbol{u}}(oldsymbol{x},t) = \int_0^T dt' \int doldsymbol{x}' arphi(oldsymbol{x} - oldsymbol{x}',t-t') oldsymbol{u}(oldsymbol{x}',t')$$

• Weak solution to the Euler eqs. (this holds for all  $\varphi$ 's)

$$\int_0^T dt \int d\boldsymbol{x} \left[ (\partial_t \varphi) \boldsymbol{u} + \boldsymbol{u} (\boldsymbol{u} \cdot \nabla) \varphi + p \nabla \varphi \right] = \boldsymbol{0}, \quad \int_0^T dt \int d\boldsymbol{x} \, \boldsymbol{u} \cdot \nabla \varphi = 0$$

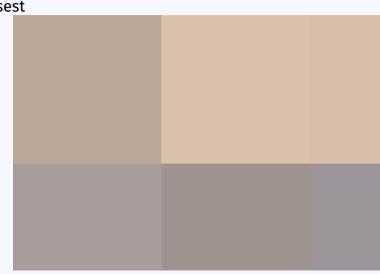
• There are famous examples of constructed weak solutions (Scheffer 1993 (2D); Schnirelman 1997 (2D), 2000 (3D)).

#### Construction (Buckmaster et al. 2019)

(Buckmaster, De Lellis, Székelyhidi, and Vicol, Comm. Pure Appl. Math. 72, 229, 2019)

- time-dependent weak solution u(x,t) x: unit periodic cube
  - t: 0 < t < T (T some large time)
- Two inputs
  - (1) Total energy  $e(t) = \int |\boldsymbol{u}(\boldsymbol{x},t)|^2 d\boldsymbol{x}$  in  $0 \le t \le T$
  - (2) Exponent  $h: |{m u}({m x} + {m r}, t) {m u}({m x}, t)| \sim r^h$ , 0 < h < 1/3
- Iterative construction (space and time)
- Initial guess:  $\boldsymbol{u}_0(\boldsymbol{x},t)$ :  $\boldsymbol{x}$  in periodic cube,  $0 \leq t \leq T$   $\boldsymbol{u}_0(\boldsymbol{x},t) \Rightarrow \boldsymbol{u}_1(\boldsymbol{x},t) \Rightarrow \cdots \Rightarrow \boldsymbol{u}_n(\boldsymbol{x},t) \rightarrow \boldsymbol{u}(\boldsymbol{x},t)$  as  $n \rightarrow \infty$   $\boldsymbol{u}_n$  has characteristic wavenumber  $\lambda_n$

 $oldsymbol{u}_0$  : coarsest



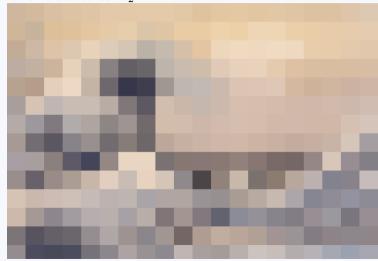
 $oldsymbol{u}_1$  : add details to  $oldsymbol{u}_0$ 



 $oldsymbol{u}_2$  : add further details to  $oldsymbol{u}_1$ 



 $oldsymbol{u}_3$  : add further details to  $oldsymbol{u}_2$ 



 $oldsymbol{u}_4$  : add further details to  $oldsymbol{u}_3$ 



 $oldsymbol{u}_5$  : add further details to  $oldsymbol{u}_4$ 



 $oldsymbol{u}_6$  : add further details to  $oldsymbol{u}_5$ 



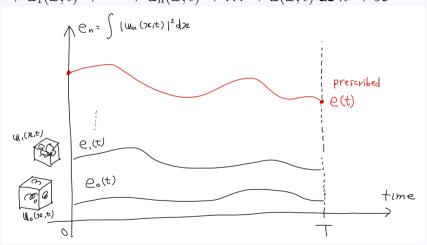
 $oldsymbol{u}_{\infty}$  :



(K. Hokusai, Thirty-six views of Mt. Fuji – the great wave off the coast of Kanagawa from Google Art Project)

# Space-time construction

$$m{u}_0(m{x},t)\Rightarrowm{u}_1(m{x},t)\Rightarrow\cdots\Rightarrowm{u}_n(m{x},t)\Rightarrow\ldots\tom{u}(m{x},t)$$
 as  $n\to\infty$ 



 $rac{de(t)}{dt} < 0$ : energy dissipation.  $m{u}_n(m{x},t)$  has maximum wavenumber  $\lambda_n$ 

Classical Euler equation (periodic cube)

$$\partial_t \mathbf{u} + (\mathbf{u} \cdot \nabla)\mathbf{u} + \nabla p = 0, \quad \nabla \cdot \mathbf{u} = 0$$

- Iterative construction from  $u_n$  to  $u_{n+1}$ 
  - *n*-th iteration:  $(u_n, p_n)$  for  $0 \le t \le T$

$$\partial_t \boldsymbol{u}_n + (\boldsymbol{u}_n \cdot \nabla) \boldsymbol{u}_n + \nabla p_n = \boldsymbol{E}_n = -\operatorname{div} \mathbf{R}_n$$

 $\boldsymbol{E}_n$ : error

 $R_n$ : positive-definite symmetric  $3 \times 3$  tensor

• Add perturbation  $(\boldsymbol{u}_{n+1}, p_{n+1}) = (\boldsymbol{u}_n + \boldsymbol{W}_n, p_n + Q_n)$ 

$$\begin{aligned} \partial_t \boldsymbol{u}_{n+1} + (\boldsymbol{u}_{n+1} \cdot \nabla) \boldsymbol{u}_{n+1} + \nabla p_{n+1} &= \boldsymbol{E}_{n+1} = -\operatorname{div} \mathsf{R}_{n+1} \\ \boldsymbol{E}_{n+1} &= \boldsymbol{E}_n + \partial_t \boldsymbol{W}_n + (\boldsymbol{u}_n \cdot \nabla) \boldsymbol{W}_n + (\boldsymbol{W}_n \cdot \nabla) \boldsymbol{u}_n + (\boldsymbol{W}_n \cdot \nabla) \nabla \boldsymbol{W}_n + \nabla Q_n \end{aligned}$$

• Idea : add perturbation  $W_n(x,t)$  to cancel error  $E_n(x,t)$ 

#### Perturbation to cancel error

• (n+1)-th iteration:  $(u_{n+1}, p_{n+1}) = (u_n + W_n, p_n + Q_n)$ 

$$\partial_t \boldsymbol{u}_{n+1} + (\boldsymbol{u}_{n+1} \cdot \nabla) \boldsymbol{u}_{n+1} + \nabla p_{n+1} = \boldsymbol{E}_{n+1} = -\operatorname{div} \mathsf{R}_{n+1}$$

$$\boldsymbol{E}_{n+1} = \boldsymbol{E}_n + \partial_t \boldsymbol{W}_n + (\boldsymbol{u}_n \cdot \nabla) \boldsymbol{W}_n + (\boldsymbol{W}_n \cdot \nabla) \boldsymbol{u}_n + (\boldsymbol{W}_n \cdot \nabla) \boldsymbol{W}_n + \nabla Q_n$$

- Idea : add perturbation  ${m W}_n({m x},t)$  to cancel error  ${m E}_n({m x},t)$ 
  - If  $\|E_{n+1}\| < \|E_n\|$ , then  $u_n$  approaches to weak solution.
  - $W_n(x,t)$ : stationary solution of the classical Euler equation
  - (scale of  $W_n$ )  $\ll$  (scale of  $u_n$ )

$$E_{n+1} \sim E_n + (W_n \cdot \nabla)W_n = -\operatorname{div} \mathsf{R}_n + (W_n \cdot \nabla)W_n = \operatorname{div} [-\mathsf{R}_n + W_n \otimes W_n] \sim 0$$

#### Two questions

• Question (1): How to calculate the error  $E_n$ ? n-th iteration:  $(u_n, p_n)$  for  $0 \le t \le T$ 

$$\partial_t \boldsymbol{u}_n + (\boldsymbol{u}_n \cdot \nabla) \boldsymbol{u}_n + \nabla p_n = \boldsymbol{E}_n = -\operatorname{div} \mathsf{R}_n$$

(The Euler eqs. :  $\partial_t u + (u \cdot \nabla)u + \nabla p = 0$ )

• Question (2): How to cancel the error  ${m E}_n + ({m W}_n \cdot 
abla) {m W}_n \sim 0$  ?

$$E_{n+1} \sim E_n + (W_n \cdot \nabla)W_n = -\operatorname{div} R_n + (W_n \cdot \nabla)W_n = \operatorname{div} [-R_n + W_n \otimes W_n] \sim 0$$

#### A way to cancel the error

• Question (2): How to cancel the error  $E_n + (W_n \cdot \nabla)W_n \sim 0$ ?

$$E_{n+1} \sim E_n + (W_n \cdot \nabla)W_n = -\operatorname{div} R_n + (W_n \cdot \nabla)W_n = \operatorname{div} [-R_n + W_n \otimes W_n] \sim 0$$

• In the sense of spatial average

$$\overline{\mathsf{R}}_n = \overline{oldsymbol{W}_n \otimes oldsymbol{W}_n}$$

## Mikado flow (six jets) as perturbation

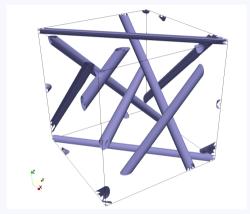
Cancel the error in the sense of spatial average

$$\overline{\mathsf{R}} = \overline{oldsymbol{w} \otimes oldsymbol{w}}$$

Six axisymmetric jets can do this

 Mikado flow

 (Daneri and Székelyhidi 2016).

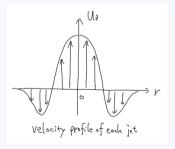


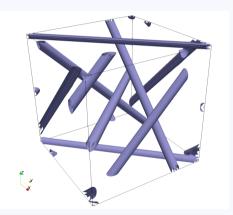
Mikado flow  $|\nabla \times \boldsymbol{w}(\boldsymbol{x})| = \text{const.}$ 

#### Mikado flow can cancel the error

- Given the error  $m{E}_n = -\operatorname{div} \mathbf{R}_n \sim \operatorname{div} m{W}_n \otimes m{W}_n$ , Spatial average:  $\overline{R}_n = m{W}_n \otimes m{W}_n$
- Mikado flow to cancel a constant, symmetric tensor R:

$$\mathsf{R} = \overline{oldsymbol{w}(oldsymbol{x}) \otimes oldsymbol{w}(oldsymbol{x})}$$





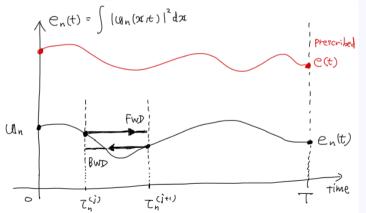
$$|\nabla \times \boldsymbol{w}(\boldsymbol{x})| = \text{const.}$$

#### How to calculate the error

• n-th iteration ( $u_n, p_n$ )

$$\partial_t \boldsymbol{u}_n + (\boldsymbol{u}_n \cdot \nabla) \boldsymbol{u}_n + \nabla p_n = \boldsymbol{E}_n = -\operatorname{div} \mathsf{R}_n$$

• "Gluing" to obtain the error  $R_n$  (Isett 2018)



## Superposition gives the error

- Classical solutions of the Euler eqs. :  $\partial_t \boldsymbol{u} + (\boldsymbol{u} \cdot \nabla) \boldsymbol{u} + \nabla p = 0$ Forward-in-time sol. from  $\tau_n^{(j)}$ :  $\boldsymbol{u}_{n,\ j}^F$ Backward-in-time sol. from  $\tau_n^{(j+1)}$ :  $\boldsymbol{u}_{n,\ j+1}^B$
- Superposition ("gluing"):  $\tilde{\boldsymbol{u}}_n = \chi_j(t)\boldsymbol{u}_{n,\ j}^F + (1-\chi_j(t))\boldsymbol{u}_{n,\ j+1}^B$   $\frac{\partial_t \tilde{\boldsymbol{u}}_n + \operatorname{div}(\tilde{\boldsymbol{u}}_n \otimes \tilde{\boldsymbol{u}}_n) + \nabla \tilde{p}_n}{\partial_t (1-\chi_j)\operatorname{div}[(\boldsymbol{u}_{n,\ j}^F \boldsymbol{u}_{n,\ j+1}^B) \otimes (\boldsymbol{u}_{n,\ j}^F \boldsymbol{u}_{n,\ j+1}^B)]}.$
- The error in terms of the tensor:

$$\mathring{\tilde{\mathsf{R}}}_{n} = (\partial_{t}\chi_{j})\mathcal{R}(\boldsymbol{u}_{n,j}^{F} - \boldsymbol{u}_{n,j+1}^{B}) - \chi_{j}(1 - \chi_{j})(\boldsymbol{u}_{n,j}^{F} - \boldsymbol{u}_{n,j+1}^{B})\mathring{\otimes}(\boldsymbol{u}_{n,j}^{F} - \boldsymbol{u}_{n,j+1}^{B})$$

 $\mathcal{R}$ : the inverse divergence operator  $\operatorname{div} \mathcal{R} u = u$ .

$$(\mathcal{R}\boldsymbol{u})^{ij} = \mathcal{R}^{ijk}\boldsymbol{u}^k,$$

$$\mathcal{R}^{ijk} = -2\triangle^{-2}\partial_i\partial_i\partial_k - \triangle^{-1}\partial_k\delta_{ii} - \triangle^{-1}\partial_i\delta_{ik} - \triangle^{-1}\partial_i\delta_{ik}.$$

• Equation for the glued velocity:

$$\partial_t \tilde{\mathbf{u}}_n + \operatorname{div}(\tilde{\mathbf{u}}_n \otimes \tilde{\mathbf{u}}_n) + \nabla \tilde{p}_n = \operatorname{div} \tilde{\mathbf{R}}_n, \quad \operatorname{div} \tilde{\mathbf{u}}_n = 0.$$

## How to en-force $|\boldsymbol{u}(\boldsymbol{x}+\boldsymbol{r})-\boldsymbol{u}(\boldsymbol{x},t)|\sim r^h$

• Input of the construction: the exponent h ( $0 \le h < 1/3$ )

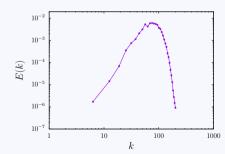
$$|\boldsymbol{u}(\boldsymbol{x}+\boldsymbol{r})-\boldsymbol{u}(\boldsymbol{x},t)|\sim r^h$$

• Mikado flow to cancel a constant, symmetric tensor R:

$$\mathsf{R} = \overline{oldsymbol{w}(oldsymbol{x}) \otimes oldsymbol{w}(oldsymbol{x})}$$



Mikado ( $|\nabla \times \boldsymbol{w}(\boldsymbol{x})| = \text{const.}$ )

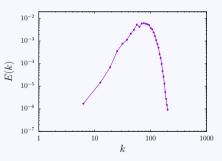


Energy spectrum of Mikado flow

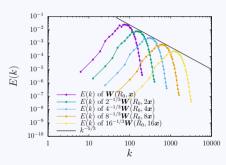
#### How to en-force the scaling $r^h$

• Perturbation  $W_n(\overline{\mathsf{R}}_n, x) \sim w(\overline{\mathsf{R}}_n, \lambda_n x)$ 

$$egin{aligned} oldsymbol{u}_{n+1}(oldsymbol{x},t) &= oldsymbol{u}_n(oldsymbol{x},t) + oldsymbol{W}_n(\overline{\mathsf{R}}_n,oldsymbol{x}) \ &= oldsymbol{u}_0(oldsymbol{x},t) + \sum A_m oldsymbol{w}(\overline{\mathsf{R}}_m,\lambda_moldsymbol{x}) \end{aligned}$$



E(k) of  $\boldsymbol{w}(\mathrm{Id},\boldsymbol{x})$  (Mikado flow)



$$E(k,t) ext{ of } oldsymbol{u}_n(oldsymbol{x},t) \sim \sum_m k_m^{-h} oldsymbol{w}(\overline{\mathsf{R}}_m,\lambda_m oldsymbol{x})$$

 $E(k,t) \propto k^{-2h-1}$  consistent to  $r^h$ 

#### Formal statement

(Buckmaster, De Lellis, Székelyhidi and Vicol 2019)

• n-th step ( $n=0,1,2,\ldots$ ) "Euler-Reynolds" equation ( $(\boldsymbol{u}_n,p_n,\mathring{\mathsf{R}}_n)$  in  $0 \le t \le T$ 

$$\partial_t \boldsymbol{u}_n + (\boldsymbol{u}_n \cdot \nabla) \boldsymbol{u}_n + \nabla p_n = \operatorname{div} \mathring{\mathsf{R}}_n, \quad \nabla \cdot \boldsymbol{u}_n = 0$$

- $u_n$ : wavenumber  $\lambda_n = 2\pi \lceil a^{b^q} \rceil$ , squared amplitude  $\delta_n = \lambda_n^{-2h}$  ( $a \gg 1, b \simeq 1 (b > 1)$ )
- Estimates

$$\|\mathbf{R}_{n}\|_{0} \leq \delta_{n+1}\lambda_{n}^{-3\alpha} = \lambda_{n+1}^{-2h}\lambda_{n}^{-3\alpha}, \|\mathbf{u}_{n}\|_{1} \leq M\delta_{n}^{1/2}\lambda_{n}, \|\mathbf{u}_{n}\|_{0} \leq 1 - \delta_{n}^{1/2}, \delta_{n+1}\lambda_{n}^{-\alpha} \leq e(t) - \int |\mathbf{u}_{n}|^{2}d\mathbf{x} \leq \delta_{n+1}.$$

 $\alpha$  suitable parameter (0 <  $\alpha$  < 1), constant M depends on h and b.

#### Three stages in the construction

Procedure to make  $u_{q+1}$  from  $u_q$  (3 stages)

(1) mollification stage:

low-pass filter larger than length  $\ell_n = \lambda_n^{-1-3\alpha/2}$ 

- (2) gluing stage
  - $0 \le t \le T$  is divided with small interval  $\tau_n$ .
  - Solve strong Euler eqs. with  $u_n^{(\ell_n)}(x,t=j\tau_n)$  as initial data
  - Superpose the forward-in-time and backward-in-time solutions.
  - Calculate the Reynolds stress R from the superposed solution.
- (3) perturbation stage
  - calculate the Mikado flow to cancel the Reynolds stress R.
  - $u_{n+1}$  = (superposed solutions) + mikado flow

#### Precise form of the perturbation

• Difference between the glued-velocity energy and the prescribed energy  $\boldsymbol{e}(t)$ 

$$\rho_n(t) = \frac{1}{3} \left( e(t) - \frac{\delta_{n+2}}{2} - \int |\tilde{\boldsymbol{u}}_n|^2 d\boldsymbol{x} \right), \quad \rho_{n,i}(\boldsymbol{x},t) = \frac{\eta_i^2(\boldsymbol{x},t)}{\sum_j \int \eta_j^2(\boldsymbol{y},t) d\boldsymbol{y}} \rho_n(t)$$

 $\eta_i(\boldsymbol{x},t)$ : cut-off function

ullet Inverse Lagrangian map of the glued velocity  $oldsymbol{ ilde{u}}_n$ 

$$(\partial_t + ilde{oldsymbol{u}}_n \cdot 
abla) oldsymbol{a}_j = oldsymbol{0}, \quad oldsymbol{a}_j(oldsymbol{x}, j au_n) = oldsymbol{x}$$

• Transform of the Reynolds stress

$$\mathsf{R}_{n,j} = \rho_{n,j} \mathrm{Id} - \eta_j^2 \mathring{\mathsf{R}}_n, \quad \widetilde{\mathsf{R}}_{n,j} = \frac{\nabla \boldsymbol{a}_j \mathsf{R}_{n,j} (\nabla \boldsymbol{a}_j)^T}{2}$$

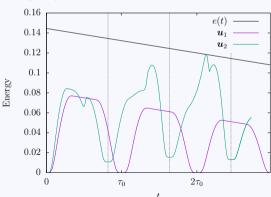
• Main part of the perturbation (w(R, x): six jets)

$$oldsymbol{W}_{o,n} = \sum_{j} [
ho_{n,j}(oldsymbol{x},t)]^{1/2} (
abla oldsymbol{a}_{j}(oldsymbol{x},t))^{-1} oldsymbol{w} \left( \overline{ ilde{\mathsf{R}}}_{n,j}, rac{\lambda_{n}}{2\pi} oldsymbol{a}_{j}(oldsymbol{x},t) 
ight)$$

• (n+1)-th step velocity  $u_{n+1} = \tilde{u}_n + W_{o,n} + W_{c,n}$  ( $W_{c,n}$  guarantees divergence-free condition)

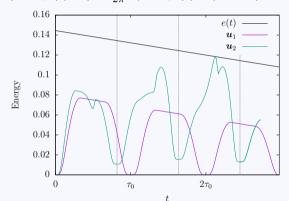
## Simulation example: parameters

- Difficulty : n-th step wavenumber  $\lambda_n = 2\pi \lceil a^{b^n} \rceil$  (periodic unit cube)
- $e(t)=e_0-At$  (linear decrease), exponent h=0.30 ( $a=3.0,b=1.15,\alpha=0.1$ )
- Initial guess :  $u_0(x,t) = 0$



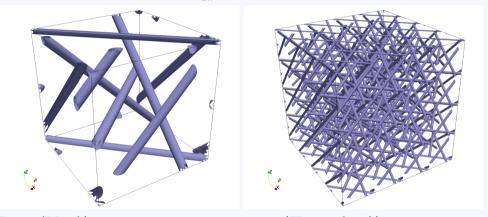
## Simulation example: energy

- n = 0:  $u_0(x, t) = 0$
- n=1:  $\boldsymbol{u}_1(\boldsymbol{x},t)=\eta_1(t)\boldsymbol{w}(\mathrm{Id},\frac{\lambda_1}{2\pi}\boldsymbol{x})=\eta_1(t)\boldsymbol{w}(\mathrm{Id},4\boldsymbol{x})$



#### Simulation example: n = 1

• n = 1:  $\boldsymbol{u}_1(\boldsymbol{x}, t) = \eta_1(t) \boldsymbol{w}(\mathrm{Id}, \frac{\lambda_1}{2\pi} \boldsymbol{x}) = \eta_1(t) \boldsymbol{w}(\mathrm{Id}, 4\boldsymbol{x})$ 

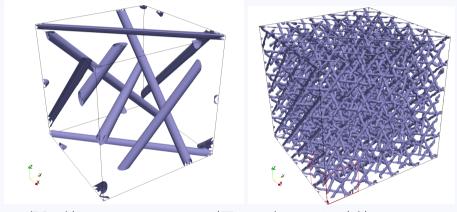


$$|\nabla \times \boldsymbol{w}(\mathrm{Id}, \boldsymbol{x})| = \mathrm{const.}$$

$$|\nabla \times \boldsymbol{u}_1(\boldsymbol{x},t)| = \text{const.}$$

#### Simulation example: n = 2

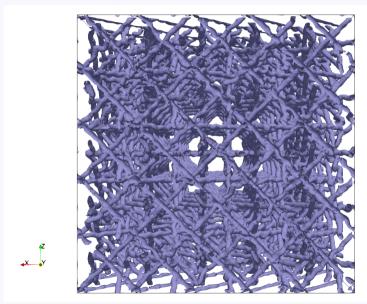
• n=2:  $\boldsymbol{u}_2(\boldsymbol{x},t)\simeq \boldsymbol{w}(\mathsf{R},\frac{\lambda_2}{2\pi}\boldsymbol{x})=\boldsymbol{w}(\mathsf{R},5\boldsymbol{x})$ 



 $|\nabla \times \boldsymbol{w}(\mathrm{Id}, \boldsymbol{x})| = \mathrm{const.}$ 

 $|\nabla \times \boldsymbol{u}_2(\boldsymbol{x}, t = 3\tau_1/2)| = \text{const.}$ 

# Simulation example: n=2



# Difficulty to obtain scaling of $m{u}_2$

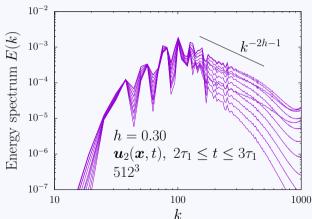
• Prescribed exponent h = 0.30

• 
$$n=2$$
:  $u_2(x,t)$   $E_n(k) \propto k^{-2h-1} = k^{-1.60}$  ???  $u_2, t = 7\tau_1/6$   $u_2, t = 9\tau_1/6$   $u_2, t = 11\tau_1/6$   $u_2, t = 11\tau_1/6$   $u_3$   $u_4$   $u_4$   $u_5$   $u_5$ 

• To get scaling at  $u_2$ , we use thicker Mikado jets.

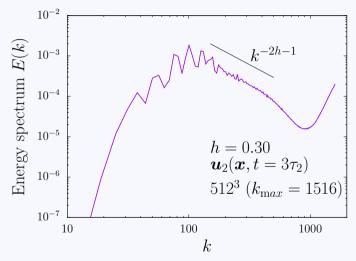
## Scaling of $u_2$ with thicker Mikados

- Prescribed exponent  $h = 0.30 \ (a = 3, b = 1.15, \alpha = 0)$
- n=2:  $u_2(x,t)$   $E_n(k) \propto k^{-2h-1} = k^{-1.60}$  ???



• Mikado radius doubled — a dirty trick to obtain scaling at n=2

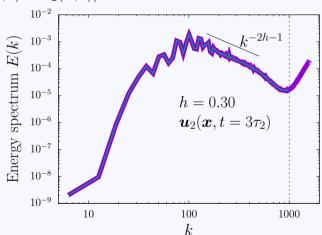
# Scaling of $oldsymbol{u}_2$ with thicker Mikados



Numerical problem: noise grows at high k.
Using thinner Mikados can cure this problem.

## Longitudinal structure function of $u_2$

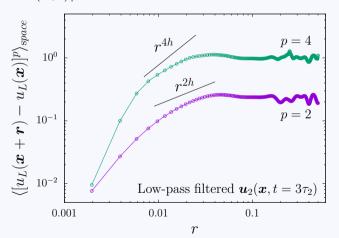
- Prescribed exponent  $h = 0.30 \ (a = 3, b = 1.15, \alpha = 0)$
- $|{\bm u}_2({\bm x}+{\bm r},t)-{\bm u}_2({\bm x},t)|\sim r^h$



• k > 1000 part is removed (low-pass filter).

## Longitudinal structure function of $u_2$

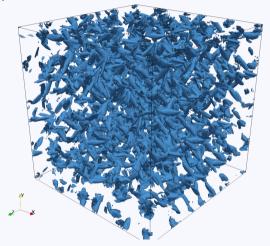
- Prescribed exponent  $h = 0.30 \ (a = 3, b = 1.15, \alpha = 0)$
- $|{\bm u}_2({\bm x}+{\bm r},t)-{\bm u}_2({\bm x},t)|\sim r^h$



• Order p=2 and 4: consistent with  $r^{2h}$  and  $r^{4h}$ ?

# Vorticity iso-surface of $oldsymbol{u}_2$

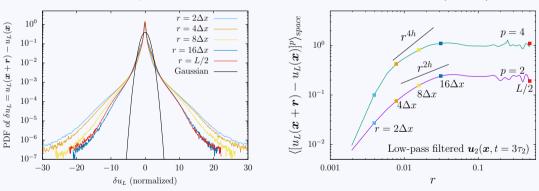
• Prescribed exponent  $h = 0.30 \ (a = 3, b = 1.15, \alpha = 0)$ 



• Low-pass filtered  $\boldsymbol{u}_2(\boldsymbol{x}, 3\tau_2)$ 

## PDF: longitudinal velocity increment $oldsymbol{u}_2$

• Prescribed exponent h = 0.30 ( $a = 3, b = 1.15, \alpha = 0$ ),  $u_2(x, 3\tau_2)$ 

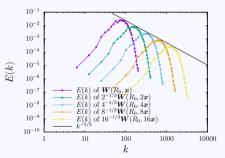


Normalized PDFs in the "scaling range" do not collapse?

#### Discussion

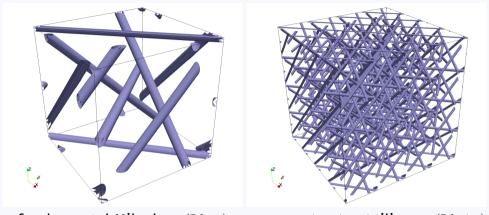
Insight from the mathematical construction?

Prescribed (single) exponent  $h: |{m u}({m x}+{m r},t)-{m u}({m x},t)| \propto r^h$  — how we tile the Mikado flows, not the profile of each jet



• Question: is the constructed solution multi-fractal or not?  $\langle [u_L(\boldsymbol{x}+\boldsymbol{r},t)-u_L(\boldsymbol{x},t)]^p \rangle \not\propto r^{ph}$ ?

## Tiling of the Mikado flows



fundamental Mikado  $oldsymbol{w}(\mathrm{Id},oldsymbol{x})$ 

 $4 \times 4 \times 4$  tiling:  $\boldsymbol{w}(\mathrm{Id}, 4\boldsymbol{x})$ 

Can we introduce an in-homogeneous factor for each sub-cube?

— reminiscent of cascade models of turbulence

#### Summary and outlook

#### Summary

- Mathematical construction of dissipative Euler solutions by De Lellis, Székelyhidi and co-workers
- Numerical simulation of the construction hopefully with scaling (on-going)

#### Outlook

- Optimize Mikado thickness to obtain scaling with n = 2, 3, 4.
- Increase n (iteration) with larger resolution.
- Check the scaling  $\langle \{[{m u}({m x}+{m r},t)-{m u}({m x},t)]\cdot \hat{{m r}}\}^p\rangle \propto r^{\xi_p}$ In particular, the 3rd order? (Duchon-Robert?) Are the constructed solutions multi-scaling (intermittent)?
- Can we relate the construction to cascade models?
- Adapt to lower dimensional flows (e.g., surface quasi-geostrophic (SQG) model).